

30-11-20

• Επανάληψη των προηγούμενων (θεωρήματα 12, 13, 14, 15)

• Μη ομογενείς γραμμικές εξισώσεις με σταθερούς συντελεστές.

$$a_n y^{(n)}(t) + a_{n-1} y^{(n-1)}(t) + \dots + a_1 y'(t) + a_0 y(t) = b(t), t \in I, a_i \in \mathbb{R} (i=0, \dots, n), b \in C(I)$$

(I) Η μέθοδος των αγνώστων σταθερών.

• $b(t) = p_m(t)$, $a_0, \dots, a_{n-1} = 0 \rightarrow y_\mu(t) = p_m(t)$

(Πx)

Παράδειγμα 3i: $y^{(4)} + y'' = t^3 + 1$.

$$\rightarrow y_\mu'' = at^3 + bt^2 + ct + d$$

$$\rightarrow y_\mu'' = t^3 - 6t + 1$$

$$\rightarrow y_\mu = \frac{1}{20} t^5 - t^3 + \frac{1}{2} t^2$$

• $b(t) = e^{kt} p(t) \rightarrow y_\mu(t) = z(t) e^{kt}$

(Πx)

Παράδειγμα 3iii: $y''' + y'' + 2y = t^2 e^{-2t}$

$$y_\mu = z e^{-2t}$$

$$\Rightarrow z''' - 5z'' + 8z' - 2z = t^2$$

$$\Rightarrow z_\mu = at^2 + bt + c$$

$$\Rightarrow z_\mu(t) = -\frac{1}{2} t^2 - 4t - \frac{7}{2}$$

• $b(t) = p(t) e^{\sigma t} \cos(\tau t), \sin(\tau t) \rightarrow y_\mu(t) = z(t) e^{(\sigma+i\tau)t}$, $\operatorname{Re} z, \operatorname{Im} z$

(Πx)

Παράδειγμα 3iv,v: $y'' - 2y' + y = t e^{-t} \sin(2t), \cos(2t)$

$$\Rightarrow y'' - 2y' + y = t e^{-t+i2t}$$

$$\Rightarrow y_\mu = z e^{-t+i2t}$$

$$\Rightarrow z'' + 4(-1+i)z' - 8iz = t$$

$$\Rightarrow z_\mu(t) = bt + c$$

$$\Rightarrow z_1 = \frac{1}{8}it + \frac{1}{16}(-1+i)$$

$$\Rightarrow y_1(t) = z_1(t)e^{-t+i2t} = e^{-t}[\cos 2t + i \sin 2t] \left[\frac{1}{8}it + \frac{1}{16}(-1+i) \right]$$

$$\Rightarrow \operatorname{Re} y_1(t) = e^{-t} \left[-\frac{1}{16} \cos(2t) - \frac{1}{8} \left(t + \frac{1}{2} \right) \sin(2t) \right]$$

(ix)

Άσκηση B-43: $y'' - 2by' + cy = 0$, b, c σταθερές, y : λύση

$$y(0) = y(1) = 0 \rightarrow y(n) = 0, n \in \mathbb{Z}$$

Λύση: Χαρακτηριστικό πολυώνυμο: $\lambda^2 - 2b\lambda + c = 0$

$$\text{Ρίζες: } \lambda_{1,2} = b \pm \sqrt{4b^2 - 4c} \Rightarrow \lambda_{1,2} = b \pm \sqrt{b^2 - c}$$

(i) $b^2 > c$:

$$y_1 = e^{\lambda_1 t}, y_2 = e^{\lambda_2 t}, \lambda_1 \neq \lambda_2, \lambda_1, \lambda_2 \in \mathbb{R}$$

$$y(t) = c_1 y_1(t) + c_2 y_2(t) = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$$

$$y_1(0) = 0 \rightarrow c_1 + c_2 = 0$$

$$y_1(1) = 0 \rightarrow c_1 e^{\lambda_1} + c_2 e^{\lambda_2} = 0 \Rightarrow c_1 = c_2 = 0$$

(ii) $b^2 = c$

$$\rightarrow y(t) = c_1 e^{\lambda t} + t e^{\lambda t}, \lambda = b$$

$$\Rightarrow c_1 = c_2 = 0$$

(iii) $b^2 < c$

$$\delta = \sqrt{c - b^2}$$

$$\lambda_{1,2} = b \pm i\delta$$

$$y(t) = c_1 e^{bt} \cos(\delta t) + c_2 e^{bt} \sin(\delta t)$$

$$y(0) = 0 \Rightarrow c_1 + c_2 e^0 \sin(0) = 0 \Rightarrow c_1 = 0$$

$$y(1) = 0 \Rightarrow c_2 e^b \sin(\delta) = 0 \Rightarrow \delta = k\pi$$

$$\rightarrow y(t) = c_2 e^{bt} \sin(k\pi t) = y_2$$

$$t \in \mathbb{R} \Rightarrow y_2(t) = 0$$